# The GMRT: System Parameters and Current Status

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This document gives an overview of the latest status of the GMRT and some relevant system parameters. Section 1 gives the background and an overall description of the GMRT, covering the legacy system, as well as the GMRT upgrade. Section 2 gives the current status, including that of the upgrade, and is the part more relevant to those planning an observation.

## 1 General Overview

The GMRT consists of thirty 45 m diameter antennas spread over a 25 km region. Half the antennas are in a compact, quasi randomly distributed array with a diameter of about 1 km. The remaining antennas are on 3 arms of length  $\sim 14$  km (NorthWest, NorthEast and South) with 5 or 6 antennas on each arm. The longest baseline is about 25 km and the shortest is about 100 m without foreshortening. The array configuration is shown in Fig. 1.

The telescope (Latitude=19.1°N, Longitude = 74.05°E) is located near Khodad village, which is about 80 km north of Pune. The telescope site houses laboratories, guest house, library and canteen. The observatory can be reached using the daily shuttle service starting from NCRA, Pune at 7 AM in the morning (all days including holidays and weekends), or by direct taxi from Mumbai or Pune. The closest town, Narayangaon, is about 14 km from the observatory and is connected to Pune and Mumbai by public bus transport system. If advance information is given, arrangements can be made to transport observers from the Narayangaon bus stand to the observatory. See http://www.ncra.tifr.res.in for more details on various general aspects about observing at the GMRT, including a road-map for travel to the observatory.

The GMRT has been open to the international community of users since early 2002, via a proposal submission and approval scheme that presently runs two observing cycles in each year. Recently, after about a decade of operations, the GMRT has undergone a major upgrade of its capabilities. The upgraded GMRT (also referred to as the "uGMRT"), now almost complete, has been made available to the user community in a phased manner over the last 2 years or so. Sections 1.1 to 1.4 describe the existing GMRT system (also referred to as the "legacy system") that has been available to the users for the last several years, whereas section 1.5 describes the changes and improvements brought about with the uGMRT.

#### 1.1 Antennas & Feeds

The GMRT antennas are 45 m alt-azimuth mounted parabolic prime-focus dishes. While the dishes can go down to an elevation of  $16^{\circ}$ , at present, the elevation limit has been set at  $17^{\circ}$ , giving a declination coverage from  $-53^{\circ}$  to  $+90^{\circ}$ . The usable hour-angle range for different declinations is shown in Fig. 2. The slew speed of the antennas is  $20^{\circ}$ /min on both axes and they are not operated when winds are higher than 40 km/h. There is a rotating turret at the focus on which the different feeds are mounted. The feeds presently available are the 151, 325, 610/235 and the 1000-1450 MHz feeds <sup>1</sup>. The reflecting surface is formed by wire mesh and the efficiency of the antennas varies from 60% to 40%, from the lowest to the highest frequency. Both the orthogonal polarisations are brought to the control room from each antenna. The polarisations are circular for all feeds except the 1420 MHz feeds, which are linear. The 610 and 235 MHz feeds are coaxial, allowing simultaneous dual frequency observations to be carried out at these two frequency bands, albeit for only one polarisation

<sup>&</sup>lt;sup>1</sup>See the upgrade section for update on changes to these feeds

per band. However, due to the upgrade this feed is getting replaced with a broad band feed covering 550 to 850 MHz, and such dual frequency observations are no longer possible – please refer to Section 2.5 for details for the current status.

#### **1.2 Receiver Electronics**

At the focus of each antenna, each feed has 2 low noise amplifiers (one for each polarisation), with a noise injection facility where the user can select one of 4 levels of injected noise power. The two signals from each feed go to a common box (also on the feed turret) where the user can select which feed frequency signals appear at the output of the common box, since only 2 RF cables go down to the antenna base. The common box has facilities for the user to select solar attenuators (0, 14, 30 or 44 dB), enable/disable noise and Walsh modulation, and swap the two polarisation channels.

At the antenna base, the RF signals are mixed with a pair of coherent local oscillator signals (the  $1^{st}$  LO) to give two 70 MHz IF signals. The user can select the  $1^{st}$  LO frequency (1 MHz steps upto 350 MHz and 5 MHz steps from 350 to 1700 MHz), IF attenuators (0 to 64 dB in 0.5 dB steps) and the IF bandwidth (6, 16 or 32 MHz) independently for each IF. The IF signals from each antenna go to the Central Electronic Building (CEB) through an optical fibre. There is a facility at each antenna to turn on or off an Automatic Level Controller (ALC) before the optical modulator.

At the CEB the IF signals for the two polarisations from each antenna are converted to corresponding baseband signals. In the present arrangement, the signals are first converted to a common 70 MHz IF (using a different  $3^{rd}$  LO for each polarisation), and then to baseband using a single oscillator (the  $4^{th}$  LO), which the user can set from 50 to 90 MHz in steps of 0.1 KHz. For simplicity, for each polarisation, an effective value of the LO signal down conversion is specified (called the  $5^{th}$  LO).

#### 1.3 Software based back-end

The main back-end for the legacy system is the GMRT software back-end (GSB) which has been in operation since GMRT Observing Cycle 20. The GSB handles the full 32 MHz baseband signals from each of two polarisations for all 30 antennas, which are digitised and sent to a networked cluster of PCs that performs all the operations needed to realise a correlator and a pulsar receiver, in real time. The standard processing features include gain equalisation, integer and fractional delay correction and fringe stopping for the signals from each antenna. The GSB implements a FX type correlator, with user selectable number of spectral channels across the band. Operation over narrower bandwidths is supported by use of a digital filter followed by desampling to the required Nyquist rate, inside the GSB. Though the GSB works for 32 MHz input bandwidth (with an exact sampling rate of 66.666 MHz and 4 bits per sample), it can also run in 33.333 MHz sampling rate (with 8 bits per sample), which is useful for cases where the input bandwidth is limited (at the IF stages) to 16 MHz or less. These two modes of operation of the GSB are referred to as "32 MHz" and "16 MHz" modes. In both these modes, the GSB can be run either in total intensity mode or in full polar mode. In the latter, the GSB provides the intensity for each polarisation and the real and imaginary parts of the cross-term. The visibilities are output from the GSB cluster at a nominal rate of 2 seconds and are further processed by a software chain which allows real-time monitoring of the data products, before recording to disk with a default

integration time of 16 seconds.

The GSB also has a beam former, running concurrently with the FX correlator, which produces incoherent array (IA) and phased array (PA) beam outputs for a user selectable set of antennas, which can be chosen independently for the IA and PA modes. The input signals to the beam former are the outputs of the Fourier transform stage of the FX correlator, for each of two polarisations from each antenna. Whereas the IA beam former provides only total intensity samples, the PA output can be either total intensity or full polar. In the latter case, 4 terms are available – the intensities for each polarisation and the real and imaginary parts of the cross-product – from which the complete Stokes parameters can be reconstructed. The GSB includes the facility of phasing the array by observing a point source calibrator in interferometric mode to estimate the phases for both polarisations of each antenna, and correcting for these phases of the signal path after the FFT. The intensity products from the GSB beam former can be output from the GSB cluster at a fastest sampling rate of 30  $\mu$ sec, when there are 256 spectral channels across the band. For larger number of channels, the fastest rate is correspondingly slower, e.g. 60  $\mu$ sec for 512 channels. Down stream software provides options for further time integration (in powers of 2 times the input rate) and frequency integration, dedispersion and synchronous folding for pulsar observations. The final, reduced rate data can be recorded on hard disks and then backed up on SDLT or LTO tapes. The final time resolution achievable in the recorded data is a function of these various operations, in combination with the disk recording rate. The GSB beam former also has the capability to produce the raw, full time resolution phased array voltage beam output for each of two orthogonal polarisations.

The GSB also has an offline mode, where the raw voltage data from all the antennas can be recorded on an array of SATA disks attached to the GSB cluster, for offline processing. In this mode, the GSB can record data samples at reduced bit resolution, typically 4 bits per sample (for the "16 MHz" mode) and 2 bits per sample (for the "32 MHz" mode).

The entire operation of the GSB is controlled by a set of user friendly functions implemented in a graphical user interface (GUI). The GSB is interfaced to the main control and monitor software of the GMRT. The output data of the GSB are compatible with the existing data formats at the observatory, for the interferometry and beam modes.

#### 1.4 Control System

In addition to issuing commands to slew and track the antennas, one can issue commands to set the parameters of the electronics. The control system also provides facilities for monitoring a range of parameters. In practice, the array is controlled by the telescope operator on duty and the role of the user is to create an OBSERVE file and ensure that the data quality is satisfactory.

Several tools are available in http://www.gmrt.ncra.tifr.res.in/~astrosupp/ for creating command files, setup files, calculation of source rise and set times, to select phase calibrators from VLA calibrator list, etc.

#### 1.5 The Upgraded GMRT

A major upgrade of the GMRT has been underway for the last few years, and is now practically complete. The main goals of this upgrade have been to provide (i) as far as possible, seamless frequency coverage from 50 to 1500 MHz (ii) improved sensitivity with

better quality receivers (iii) a maximum instantaneous usable bandwidth of 400 MHz (iv) a revamped and modern servo system (v) a new generation monitor and control system (vi) improvements in the antenna mechanical structure and (vii) matching improvements in infrastructure and computational facilities. The upgrade has resulted in significant changes to almost all aspects of the GMRT receiver chain and other systems. However, full care has being taken in the design of the new systems to ensure that the performance of the existing legacy GMRT system is not affected as the upgrade is implemented.

In feeds and front-end electronics, the existing 325 MHz feed has been replaced with a broadband feed operating from 250 to 500 MHz, along with a broadband low noise amplifier with improved noise temperature. A new feed operating from 550 to 850 MHz has replaced the existing 610/235 MHz co-axial feed, also with a matching LNA with an improved noise figure. Due to this, the 235 MHz band of the legacy system is no longer available from Cycle 34 (April 2018 onwards). The 150 MHz feed has also been replaced with a wider bandwidth feed, covering 120 to 240 MHz. As far as possible, it has being ensured that the new feeds will cover the frequency range provided by the existing narrow band feeds that they replace, with similar or better level of sensitivity. The optical fibre link to each antenna has been modified to provide additional wavelengths to bring back the broadband RF signals directly to the receiver room, without disturbing the existing narrow bandwidth path that brings back the two IF signals. In the receiver room, a separate and parallel signal path has been developed to convert the broadband RF signals to baseband signals with a maximum bandwith of 400 MHz, which are processed with a new digital back-end system (correlator + beamformer + pulsar receiver), that can handle the full 400 MHz bandwidth. This entire chain runs in parallel with the existing 32 MHz bandwidth receiver chain of the legacy system, without affecting its performance in any way.

The servo system for all 30 antennas has been upgraded with new brushless DC motor system along with a new servo computer. A modern monitor and control system with improved hardware at each antenna connected to the central station via Ethernet is coming up in parallel with the existing system. It will be supported with improved high level software at the central control room. Several improvements to the mechanical structure and reflecting surface of the antennas are also being undertaken. Matching enhancements in computing resources and data archiving capabilities are being implemented.

Most of these upgrade activities are in the final stages of implementation and commissioning, with many of them having completed full installation and release. As different systems get completed, there have been phased releases of the uGMRT to the user community (on a shared risk basis), at each new GTAC observing cycle. The first release was from Cycle 30 (April 2016 onwards), the second was from Cycle 31 (October 2016 onwards), the third was from Cycle 32 (April 2017 onwards), and the fourth and fifth were from Cycle 33 (October 2017 onwards) and Cycle 34 (April 2018 onwards), respectively. A near final release of the uGMRT system is expected from Cycle 35 (October 2018 onwards).

## 2 PRESENT STATUS (June 2018)

This section describes the current status of the various systems and modes of the GMRT. Sections 2.1, 2.2 & 2.3 cover primarily the existing legacy GMRT system, whereas section 2.4 describes the status of the uGMRT system (including plans for the next release from October 2018 onwards), and section 2.5 talks about the ongoing upgrade activities and plans for science observations during GMRT Observing Cycle 35 (starting from October 2018).

#### 2.1 Interferometric Observations

From GMRT Observing Cycle 20 onwards, the GSB is the observatory back-end for the legacy GMRT system. All 30 antennas are in use and feeds for all frequencies are available, except for some disturbances due to upgrade activities (see section 2.5). Programs that critically depend on the short spacing antennas (C05, C06 and C09, with  $\sim$  100 m separation) must indicate this in the observing proposal. Rotation of the feed system to change the frequency of observation is now possible fairly routinely, and requires about 1 hour for rotation and for set-up at the new frequency of operation, including antenna pointing. A pointing model has been in use since GMRT Observing Cycle 15, which can be applied online during the observations; it updates the antenna pointing offsets at the start of source scan during an observing run, using commands included in the user's observe file. This procedure takes couple of minutes. If a user want to apply the dynamic pointing model, the control room should be informed before the start of the observing run.

The radio frequency interference (RFI) environment can be bad at 150 MHz and is also sometimes a problem at 235 MHz; the situation is usually better at night, than during day time. For these two bands, it is recommended to use the solar attenuators in the common box, to minimize the possibilities of saturating the downstream electronics chain due to RFI. Observations at 325 MHz can be hampered sometimes due to RFI from nearby aviation related activity, especially during day time. Due to increasing interference from mobile phone signals around 950 MHz, the all-pass mode at L-band is no longer supported as an official mode, and consequently observations below 1000 MHz in this band are not supported. Even for the lowest of the 4 sub-bands of the L-band (covering  $1060 \pm 60$  MHz), the user is advised to check for effects of RFI. Due to proximity to the Solar maximum, night time scintillation is common, even at 1400 MHz, and the probability of scintillation is higher closer to the equinoxes. Winds can stop observations in the pre-monsoon months of April – June and also sometimes in October – November. During the monsoon months of June – July the antennas on the arms sometimes fail due to power outages.

The GSB back-end supports a maximum bandwidth of 32 MHz. However, users should consult the observatory regarding usable RF bandwidth at the lower frequencies because of RFI. For 150 MHz and 235 MHz, the recommended IF bandwidth is 6 MHz; however, 16 MHz is also usable, albeit with some caution. Polarisation observations are now routinely possible, though the user has to take some care about calibration issues. Walsh and Noise Cal modulation for real time Tsys measurements are currently not supported and hence, absolute flux calibration in regions where the system temperature varies (like the galactic plane) is not automatic. All observations are in the spectral mode and users should include a bandpass calibrator, even if doing continuum observations. Normal integration times used are 8 or 16 s but more rapid sampling (down to 2 s) can be done, subject to the availability of enough disk space for recording the larger data volume. Users wanting such modes should consult the operations group at the observatory (contact: gmrtoperations@ncra.tifr.res.in). Mosaicing with the GMRT has not been fully debugged.

Various tools have been developed to look at the data in quasi real time. Some of the most used tools are **mon** (displays real time snapshots of cross correlations, self-power, antenna bandshape, phase and amplitude etc), **tax** (gives offline plots of cross correlations, self-power, antenna bandshape, phase and amplitude etc), **ggdp** (gives information on nonworking antennas, bad baselines, phase jumps, delay jumps etc). These tools are available for all users and can be run with some help from on duty telescope operators. Users can also find several useful tools in http://www.gmrt.ncra.tifr.res.in/~astrosupp/ for creating command files, setup files, calculation of source rise and set times, to select phase calibrators from VLA calibrator list, etc. These are especially useful for users who are availing of the absentee observing facility at GMRT. For users interested in polarisation data at bands other than L band, an analysis recipe in NRAO AIPS is now available.

The data from the GMRT can be converted to FITS files using locally developed software, and analysed in standard packages like AIPS. These can be backed up on DVDs or external hard disks, written by Linux machines. Users should bring their own media for backing up the data. Facilities for analysing GMRT data are available both at the Observatory and at NCRA, Pune. Users wanting extensive computing facilities or large amounts of disk space for data storage or analysis should make their requirements known well in advance (contact: gmrtoperations@ncra.tifr.res.in).

Table 1 gives the measured system parameters of the GMRT, and some useful numbers for estimating the required observation time, for the legacy system. Basic system parameters of uGMRT is given in Table 2. Additional information can be found at the GMRT subsection of the NCRA home page (http://www.ncra.tifr.res.in).

#### 2.2 Pulsar observations

The GSB beam former and pulsar receiver allows incoherent and phased array mode observations using all the 30 antennas, with a maximum bandwidth of 32 MHz. For incoherent array mode observations, the actual number of antennas that can be gainfully added depends on the quality of the signals from the antennas, including effects of receiver instabilities and RFI. Besides varying with time, these effects also vary with the radio band being used and from central square to arm antennas. The final multi-channel data from the IA beam output can be recorded either on disk or on tapes (SDLT or LTO). Due to the current limitations of the data acquisition system, the fastest sampling achievable in the incoherent array mode is 60  $\mu$ sec for the 256 channel, 16 or 32 MHz modes of the GSB. This becomes 120  $\mu$ sec for the 512 channel, 16 or 32 MHz modes. Faster rates are possible at the expense of reduced spectral resolutions.

For the phased array mode of observations, there is an algorithm that can phase any selected number of available, working antennas (each polarisations independently) using interferometric observations of a point source calibrator. The phasing for central ( $\sim 14$ ) antennas works well for time scales ranging from one hour to a few hours, depending on the operational frequency and the ionospheric conditions. For arm antennas, the de-phasing can be more rapid. Polarimetric pulsar observations are possible with the GSB, but instrumental polarisation effects for the GMRT are not fully characterised and observers will therefore need to carry out their own calibration.

The phased array data from the GSB can also be recorded on disk or tapes (SDLT or LTO). Either the total intensity signal or the 4 polarisation terms can be recorded. For total intensity, the fastest sampling rate currently supported is 60  $\mu$ sec for the 256 channel, 16 and 32 MHz modes of the GSB, and is 120  $\mu$ sec for the 512 channel, 16 and 32 MHz modes. For the polar mode, the fastest sampling times are slower by a factor of 2 than these numbers, for the corresponding GSB modes. Both IA and PA mode data are available with a time tagging facility that is accurate to ~300 nanosec with respect to GPS and timing observations can be carried out using these. The format of the beam data from the GSB is identical to that provided by the older pulsar back-ends.

The PA mode of the GSB also includes capability for recording the full time resolution voltage beam data, which can be used for applications such as off-line coherent dedispersion. A real-time coherent dedispersion pipeline is also available since Cycle 31. The GSB also allows a mode where the single IA and PA beams can be replaced by two IA beams or two PA beams, with independent antenna selections for each. This facilitates simultaneous dual-frequency observations of pulsars using the sub-array mode of the GMRT. Users should note that such observations involve special scheduling considerations, due to feed rotations and related overheads.

#### 2.3 Observing modes with the GSB

The GSB presently supports the following modes of observations: (i) full bandwidth, nonpolar and full polar interferometric observations in the "16 MHz" mode, with a choice of 256 or 512 spectral channels across the full band, with integration times 2 seconds and larger. (ii) full bandwidth, non-polar and full polar interferometric observations in the "32 MHz" modes, with a choice of 256 spectral channels for both non-polar and full polar interferometric observations and 512 channels for non-polar interferometric observations across the full band, with integration times 2 seconds and larger. (iii) spectral zoom modes (for spectral line observations) where the input band is filtered and decimated by factors 4,8,16...128, while keeping the number of spectral channels across the reduced bandwidth fixed at 256 or 512 - this mode will only work within the "16 MHz" mode; (iv) IA and PA beam modes with total intensity output, with fastest sampling time of 60  $\mu$ sec, at present (resolution in the final recorded data subject to constraints described in section 2.2); (v) PA beam mode with full polar output at correspondingly reduced time resolutions (as described in section 2.2); (vi) variable spectral resolution, with a choice of 64,128,256 or 512 spectral channels across the band of observation. Reduced spectral channels will allow for correspondingly faster dump times for the visibility data; (vii) full time resolution voltage beam data for "16 MHz" and "32 MHz" modes; (viii) multi-subarray beam modes (IA or PA) with full bandwidth, for up to 2 sub-arrays, with independent GAC antenna selection control for each sub-array; (ix) raw voltage recording of the digitised voltage signals from each antenna (4 bit samples) for "16 MHz" mode, followed by limited capability for offline playback and correlation / beam forming – the frequency of usage of this mode of operation will be restricted by the total volume of disk space available for recording, as well as the time taken for the offline analysis; the observatory will be able to offer very limited capabilities for long-term backup of the raw voltage dump data and the user will be responsible for clearing the large volumes of data from the disks within a stipulated time, typically a week or less. (x) Realtime coherent dedispersion mode attached to the raw voltage mode of the phased array beamformer, working for both "16 MHz" and "32 MHz" bandwidths. This mode takes the raw voltage mode signals for both polarisations from the phased array output, and produces coherently dedispersed intensity time series with a user selectable integration time, for each polarisation.

Users wanting to use the last 2 modes above should check with the observatory well in advance (contact person : Yashwant Gupta/Sanjay Kudale, ygupta/ksanjay@ncra.tifr.res.in). Current status and latest news about the GSB can be found at the GMRT home page under the "Subsystems" section.

### 2.4 Observing with the upgraded GMRT (uGMRT) system

The fifth phase of the uGMRT system was released to users from GTAC Cycle 34 (April 2018 onwards), with a combination of features and modes in either "regular release" or "shared risk" status. Since then, some new features and modes have been added and some have moved from "shared risk" to "regular release" status. The next phase of the release from Cycle 35 (April 2018 onwards) will see a few new features and modes available for users, some of which will be available for use on a shared risk basis : in such cases, the modes are not guaranteed for performing up to the specs; the user shares the risk of failure and/or under-performance of these modes, and should be ready to use these on an "as is, where is" basis; as a corollary, no make-up time will be allotted for failure / under-performance of these modes.

This new release from October 2018 onwards, targets a major fraction of the final uGMRT system, and aims to provide the following configuration and specifications to the end user :

1. Front-End (FE) + Optical Fibre (OF) systems :

1.1. All 30 antennas with L-band (Band-5) FE system (1000-1460 full-band & 4 subbands) in regular release mode. The FE box has features such as noise injection, temperature and total power monitoring facilities, which will be available in shared risk mode.

1.2. All 30 antennas with 550-850 MHz (Band-4) wideband FE system :

550-850 MHz feed + matching LNA & full-band band pass filter + 4 sub-band filters + notch filters for known sources of RFI such as television transmitters and mobile phone bands – available in regular release mode. The final FE box has additional features such as, noise injection, temperature and total power monitoring facilities, which will be available in shared risk mode.

1.3. All 30 antennas with 250-500 MHz (Band-3) wideband FE system :

250-500 MHz feed + matching LNA & full-band band pass filter + 4 sub-band filters + notch filters for known source of RFI such as television transmitters – available in regular release mode. The final FE box has additional features such as, noise injection, temperature and total power monitoring facilities, which will be available in shared risk mode. It is clarified that with these configurations, it is possible to carry out narrow band observations (32 MHz) in the frequency range of existing legacy system.

1.4 All 30 antennas with 120-240 MHz (Band-2) wideband FE system, in regular release mode :

120-240 MHz feed + matching LNA & full-band band pass filter + notch filters for known sources of RFI such as television tranmitters. The final FE box has additional features such as, noise injection, temperature and total power monitoring facilities. Note that the Band-2 system is much more prone to strong RFI effects than the other bands of uGMRT, and all the implications of the RFI may not be fully characterised and understood.

1.5. All 30 antennas with wideband OF system, delivering the full wideband signals to the back-end system.

2. Back-End (BE) systems :

2.1. Analog section : GMRT Analog Backend (GAB) for all 30 antennas : Convert any of the RF bands to baseband, with final BW of 100/200/400 MHz. Common LO settings for all antennas (both polarisations), 10-1500 MHz, 1 Hz step. Variable attenuation control for power equalisation.

Note : small improvements and additions will continue to be made to this released system, as per the overall plan.

2.2. Digital section : GMRT Wideband Backend (GWB) for all 30 antennas, with following features in regular or shared risk release mode :

 $2.2.1. \ Interferometric \ modes:$ 

(a) Total intensity and full polar modes for 100/200 MHz BW choices with 2K channels and total intensity mode for 400 MHz BW with 2K channels (regular release).

(b) Total intensity narrow bandwidth spectral line modes, with details as specified in the SOP for the GWB (regular release).

2.2.2. Beam modes (can be in parallel with the interferometric modes in 2.2.1):

(a) Option for upto 4 total intensity (IA or PA) beams for 100/200/400 MHz BW choices (regular release mode).

(b) Option for PA voltage beam on 2 out of the 4 beams for 100/200 MHz BW choices with real-time coherent dedispersion (over sub-bands) resulting in multi-channel intensity data at desired time resolution (regular release mode).

(c) Full polar mode for 2 PA beams for 100/200 MHz BW choices (regular release) and 400 MHz BW (shared risk release).

(d) Range of choices for integration time - from 0.6s to 16s and number of channels - from 2K to 16K (see 2.4.1)

2.3. Common back-end features :

(a) Upto 4 K spectral channels for most of the above modes (regular release); for other extreme combinations of number of channels and integration times (shared risk release) – system may not work reliably for lack of adequate i/o or recording capabilities at higher channels and shorter integration time.

(b) Phasing of the antennas using standard procedure (regular release); additional mode called "wideband phasing" (shared risk release).

(c) Standard power equalisation scheme for balancing the power levels for all working antennas, using the GAB attenuators (regular release); more advanced power equalisation schemes to facilitate Galactic plane / Galactic centre observations (shared risk release).

(d) Recommended settings of GAB LO for all the "standard modes" of observing for Band-3, Band-4 and Band-5, including full band and all sub-bands (regular release).

NOTE : It is to be understood that not all the modes and combinations specified above under shared risk release have been tested thoroughly, and there may be undiscovered issues in some of these. Part of the aim of this uGMRT release is to allow users to exercise the system for a thorough shake-down of such modes. 3. Offline data analysis and data back-up : The existing offline programmes such as listscan and gvfits have been upgraded for making it compatible with the uGMRT data. All interferomety data acquired will be formally archived in the GMRT Observatory Archive (GOA). Note that beamformer data are presently not archived in GOA, and the user is responsible for their own back-up of such data. Though the observatory may record GWB data (for test purposes) for observations approved for the legacy system, the GWB data won't be made available for users of the legacy system. However, users with proposals approved for upgraded GMRT can use the data from both GWB and legacy system (GSB).

#### 4. Servo system :

All 30 antenna with upgraded servo system with brushless motor drives and upgraded antenna based servo computer.

### 2.5 Upgrade activities & science observations during GMRT Observing Cycle 35

The current phase of the upgrade activities of various subsystems of the GMRT demands additional downtime of antennas and facilities involved in the upgrade. As mentioned, the attempt is to minimise the disruption of the existing GMRT system while implementing the upgrade, and also to ensure that the existing system and modes continue to be supported as much as possible, even as the upgrade proceeds towards completion. In order to meet both the requirements, i.e., upgrade activities and smooth running of science observations, the observatory has been running with a new model for science operations, since Cycle 23 (October 2013 onwards). In this scheme, from Monday to Friday, science observations were scheduled only during night times, while day times were used for upgrade activities. During the week-ends (Saturday morning to Monday morning) observations were scheduled round the clock. To compensate further for lost observing time, the GMRT Observing Cycle was extended by two more weeks, to cover a total duration of five and a half months.

With the tapering down of the engineering activities related to the upgrade, the number of days reserved for day time upgraded activities was reduced from Cycle 33 (October 2017 onwards), and day times on Mondays and Fridays were made available for science observations. The same schedule will be carried forward to Cycle 35 (October 2018 onwards) also. Maintenance breaks on Wednesday and Thursday will continue throughout the cycle as per the present practice. This model of operations results in certain LST ranges having less slots available for scheduling during every cycle, and we request users to bear this in mind when preparing their observing proposals. The available IST/LST slots in Cycle 35 can be seen in a dummy schedule at http://www.ncra.tifr.res.in/ncra/gmrt/gtac. As can be noted, there are fewer time slots available for scheduling in the LST range of 16 to 24 hrs.

Some of the existing observation modes and available flexibility of settings for observations in the existing legacy system may be partially affected by the changes implemented as part of the upgrade activities. These include the following : (i) With all antennas now having the new Band-4 feed and receiver, the dual frequency 235-610 feeds and receivers of the legacy system are no longer available on any antenna; hence the simultaneous dual frequency observing mode at 235 + 610 MHz of the legacy system is no longer possibe; (ii) For some observing frequencies, the choice of  $1^{st}$  LO > RF might not be possible when observing in 250-500 MHz (Band-3) and 550-850 MHz (Band-4). In such cases, regular 325 MHz (or 610 MHz) observations in legacy mode can still be possible, with the choice of  $1^{st}$  LO < RF; (iii) Upgrades of the feed positioning servo system may result in downtime of up to one week, of one antenna at any given time; (iv) Antenna structure and surface improvement activities may result in up to 2 antennas being down during the night time for a week to one month, depending on the nature of the repair work.

The GMRT Observatory will try its best to minimise the number of antennas down at night, by coordinating the activity across the groups. The observatory will try its best to maintain the availability of a minimum of 26 antennas for all the science observations.

For further details and clarifications please contact

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	Frequency (MHz)				
	151	235	325	610	1420
Primary Beam (arc min)	186±6	$114\pm5$	$81 \pm 4$	$43 \pm 3$	$(24 \pm 2) * (1400/f)$
Receiver Temperature $(\mathrm{T_R})$	295 <sup>†</sup>	$106^{\dagger}$	53	60	45
Typical $\mathrm{T_{sky}}$ (off galactic plane)	308	99	40	10	4
Typical $T_{\text{ground}}$	12	32	13	32	24
Total System Temperature (K)	615	237	106	102	73
$(T_R + T_{sky} + T_{ground})$					
Antenna Gain (K/Jy/Antenna)	0.33	0.33	0.32	0.32	0.22
Synthesised Beam (arcsec)					
Whole Array	20	13	9	5	2
Central Square	420	270	200	100	40
Largest Detectable Source(arcmin)	68	44	32	17	7
Usable Frequency Range (MHz)					
Observatory default	150 to 156	236 to 244	305 to 345	580 to 640	1000 to 1450
Range allowed by electronics	130 to 190	230 to 250	305 to 360	570 to 650	1000 to 1450
Fudge Factor(actual to estimated time)					
For Short Observations	10	5	2	2	2
For Long Observations $^{\#}$	5	2	2	1	1
Best rms sensitivities achieved					
so far as known to us (mJy)	0.7	0.25	0.04	0.02	0.03
Typical Dynamic Ranges	> 1500	> 1500	>1500	>2000	>2000

Table 1.	Measured	System	Parameters	of the	GMRT
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† With default solar attenuator (14 dB).

# For spectral observations fudge factor is close to 1

	Table 2: System Parameters of the uGMRT				
Band	Gain	Total Tsys (K)	rms <sup>\$</sup>	Synthesised Beam	
			(microJy/bm)	(arcsec, band center)	
120 to 250 MHz	0.33	760 to 240	190	17.3	
250 to 500 MHz	0.38	165 to 100	50	8.3	
550 to 850 MHz	0.35	$105$ to $100^{\%}$	40	4.3	
1050 to 1450 MHz	0.28-0.22	80 to 75	45	2.3	

 $^{\%}$  this is for 800 MHz, at 825 MHz, T\_sys is 133 K, and T\_sys increases beyond  $^{\$}$  rms is determined assuming 30 antennas, 10min integration and 100 MHz bandwidth

Figure 1: GMRT Array configuration

Figure 2: Hour Angle at which sources at different declinations rise and set for GMRT antennas - upper curve if for elevation limit of  $16^{\circ}$  and the lower for  $20^{\circ}$